**Module 3 - Motion Path Program:** This program will cause the Roomba to follow the path shown in the Module.

```java
import roomba.roombanetwork.services.userservice.*;

public class MyRoombaProgram{

    public static void main(String [] args){
        UserService.setServerAddress("localhost");
        UserService.setName("Your Name");

        Roomba roomba = new Roomba();

        roomba.drive(3);
        roomba.turn(90);
        roomba.drive(4);
        roomba.turn(-90);
        roomba.drive(4);
        roomba.turn(-90);
        roomba.drive(6);
        roomba.turn(-90);
        roomba.drive(3);
        roomba.turn(-90);
        roomba.drive(1);
        roomba.turn(90);
        roomba.drive(2);

        UserService.disconnect();
        System.exit(1);
    }
}
```
import roomba.roombanetwork.services.userservice.*;

public class MyRoombaProgram{

    public static void main(String[] args){
        UserService.setServerAddress("localhost");
        UserService.setName("Your Name");

        Roomba roomba = new Roomba();

        roomba.drive(1);
        roomba.turn(90);
        roomba.forwardForTime(.3, 5);
        roomba.turnForTime(.3, 3);
        roomba.forwardSpeed(.3);
        roomba.turnSpeed(.3);
        roomba.pause(3);

        UserService.disconnect();
        System.exit(1);
    }
}

Module 3 - Exercise 1 Program: This program will have the Roomba move in the different possible ways.
Module 3 - Exercise 2 Program: This program will have the Roomba go forward 1 meter, turn around, and come back.

```java
import roomba.roombanetwork.services.userservice.;

public class MyRoombaProgram{
    public static void main(String [] args){
        UserService.setServerAddress("localhost");
        UserService.setName("Your Name");

        Roomba roomba = new Roomba();

        roomba.drive(1);
        roomba.turn(180);
        roomba.drive(1);

        UserService.disconnect();
        System.exit(1);
    }
}
```
Module 3 - Exercise 3 Program: This program will have the Roomba go forward 1 meter, turn left for 5 seconds, and drive backwards for 0.5 meters.

```java
import roomba.roombanetwork.services.userservice.*;

public class MyRoombaProgram{
    public static void main(String [] args){
        UserService.setServerAddress("localhost");
        UserService.setName("Your Name");

        Roomba roomba = new Roomba();

        roomba.drive(1);
        roomba.turnForTime(-.3, 5);
        roomba.drive(-0.5);

        UserService.disconnect();
        System.exit(1);
    }
}
```